

11th. World Congress on Computational Mechanics

Convergence analysis of configurational forces for brittle cracks modeled through *C*^k-Generalized FEM

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Presentation topics

- Construction of continuous **Partition of Unity** at C^k-GFEM
- Construction of a smooth approximation subspace
- Elshebian mechanics as tool to post-processing of J-integral
- Quality assessment through **global** and **local measures**
- Concluding remarks



Defining an approximation subspace

Quality assessment through global measures

Configurational forces method

Quality assessment through local measures

Smoothness, enrichments



GFEM/XFEM versus C^k-GFEM

- Regularity;
- Polynomial reproducibility;
- Efficient enrichment patterns;
- Flat-top property;
- Integration cost;
- Integration of C⁰ and C^k-GFEM.



Edge j

y⊾

Concluding remarks

C^{k} partition of unity – convex clouds

Arbitrary patch shape; Arbitrary element shape; free of coordinate mapping;

$$\xi_{j}\left(oldsymbol{x}
ight)=oldsymbol{n}_{lpha,j}\cdot\left(oldsymbol{x}-oldsymbol{b}_{lpha,j}
ight)$$

$$\begin{aligned} & \kappa \\ & \varepsilon_{\alpha,j} \left[\xi_j \left(\mathbf{x} \right) \right] = \widehat{\varepsilon}_{\alpha,j} \left(\mathbf{x} \right) \coloneqq \begin{cases} e^{-\xi_j^{-\gamma}} & \text{if } 0 < \xi_j \\ 0, & \text{otherwise} \end{cases} \quad k = \infty \\ 0, & \text{otherwise} \end{cases} \\
\begin{aligned} & \varepsilon_{\alpha,j} \left[\xi_j \left(\mathbf{x} \right) \right] = \widehat{\varepsilon}_{\alpha,j} \left(\mathbf{x} \right) \coloneqq \begin{cases} \left(\xi_j / h_j \right)^{\mathsf{P}} & \text{if } 0 < \xi_j \\ 0, & \text{otherwise} \end{cases} \quad k = p - 1 \end{aligned}$$

Edwards, C[®] finite element basis functions, Report 45, Institute for Computational Engineering and Sciences – The University of Texas at Austin, 1996

 $(\mathbf{x} - \mathbf{b}_{\alpha,j})$

 $\mathbf{n}_{\alpha, \prime}$

 $\mathbf{b}_{\alpha,j}$

x

Duarte, Kim and Quaresma, Arbitrarily smooth generalized finite element approximations. Computer Methods in Applied Mechanics and Engineering, 196 (2006)

Barcellos, Mendonca and Duarte, A Ck continuous generalized finite element formulation applied to laminated Kirchhoff plate model. Computational Mechanics, 44 (2009)



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Some improvements beyond...

C^{∞} partition of unity – convex clouds





Defining an approximation subspace

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 $q_{\alpha}^s = 4 \text{ or } 0$

Quality assessment through local measures

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Galerkin aproximation

$$\boldsymbol{u}_{p}(\boldsymbol{x}) = \sum_{\alpha=1}^{N} \varphi_{\alpha}(\boldsymbol{x}) \left\{ u_{\alpha} + \sum_{i=1}^{q_{\alpha}} \mathcal{L}_{\alpha i}(\boldsymbol{x}) b_{\alpha i} + \sum_{j=1}^{q_{\alpha}^{s}} \mathcal{L}_{\alpha j}^{s} b_{\alpha j}^{s} \right\}$$

$$\text{if } \mathbf{p=3} \quad \mathcal{L}_{\alpha 9}(x,y) = \left\{ \overline{x}, \overline{y}, \overline{x}^2, \overline{x} \ \overline{y}, \overline{y}^2, \overline{x}^3, \overline{x}^2 \ \overline{y}, \overline{x} \ \overline{y}^2, \overline{y}^3 \right\}$$

e.g.
$$\overline{x} := \frac{(x - x_{\alpha})}{h_{\alpha}}$$

for reducing mesh dependences

1.4 1.2 0.5 0.8 0.6 0.5 -0.5 0.4 0.2 -2 -2 -2 -2 Y-axis X-axis Y-axis X-axis Y-axis X-axis Y-axi X-axis $\mathcal{L}^{s}_{\alpha 4}(r,\theta) = \left\{ \sqrt{r} \sin\left(\frac{\theta}{2}\right), \sqrt{r} \cos\left(\frac{\theta}{2}\right), \sqrt{r} \sin\left(\frac{\theta}{2}\right) \sin(\theta), \sqrt{r} \cos\left(\frac{\theta}{2}\right) \sin(\theta) \right\}$

Belytschko and Black, *Elastic crack growth in finite elements with minimal remeshing*. International Journal for Numerical Methods in Engineering, 45 (1999)



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Polynomial reproducibility of the approximation

b=p+1 for C^0 PoU (conventional tent FEM shape function)

b=p for C^k PoU

p = degree of polynomial enrichment

Mendonça, Barcellos and Torres, *Robust Ck/C0 generalized FEM approximations for higher-order conformity requirements: application to Reddy's HSDT model for anisotropic laminated plates.* Composite Structures, 96 (2013)

Mendonça, Barcellos and Torres, *Analysis of anisotropic Mindlin plate model by continuous and noncontinuous GFEM.* Finite Element in Analysis and Design, 47 (2011)

Barcellos, Mendonça and Duarte, **A Ck continuous generalized finite element formulation applied to** *laminated Kirchhoff plate model.* Computational Mechanics, 44 (2009)



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branch functions on orange nodes and inside the circles, and uniform polynomial enrichment



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Convergence in terms of global values





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Configurational mechanics



$$\boldsymbol{L}^{T} \boldsymbol{\sigma}(\boldsymbol{u}) + \boldsymbol{b} = \boldsymbol{0} \text{, on } \boldsymbol{\Omega} \qquad \mathbb{L}^{T} \boldsymbol{\Sigma}(\boldsymbol{u}) + \boldsymbol{\rho} = \boldsymbol{0} \text{, on } \boldsymbol{\Omega}$$
$$= \left\{ \sigma_{x}, \sigma_{y}, \tau_{xy} \right\}^{T} \boldsymbol{b} = \left\{ b_{x}, b_{y} \right\}^{T} \qquad \boldsymbol{\Sigma} = \left\{ \Sigma_{x}, \Sigma_{y}, \Sigma_{xy}, \Sigma_{yx} \right\}^{T} \boldsymbol{\rho} = \left\{ \rho_{x}, \rho_{y} \right\}^{T}$$

Eshelby, *The force on an elastic singularity*. Philosophical Transactions of the Royal Society A: mathematical, physical and engineering sciences, 244 (1951)

Kienzler and Herrmann, *Mechanics in material space with applications to defect and fracture mechanics*. Springer, 2000

Ruter and Stein, *On the duality of global finite element discretization error control in small strain Newtonial and Eshelbian mechanics.* Technische Mechanik, 23 (2003)



Defining an approximation subspace

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Variational balance of material linear momentum

 $\boldsymbol{\Sigma} = \{\Sigma_x, \Sigma_y, \Sigma_{xy}, \Sigma_{yx}\}^T$ strong-form $oldsymbol{
ho} = \left\{
ho_x,
ho_y
ight\}^T$ inhomogeneity force $\mathbb{L}^T \mathbf{\Sigma}(\boldsymbol{u}) + \boldsymbol{\rho} = \mathbf{0}$, where Eshelby tensor $\mathbb{L} = \begin{bmatrix} \frac{\partial}{\partial x} & 0\\ 0 & \frac{\partial}{\partial y}\\ \frac{\partial}{\partial y} & 0\\ 0 & \frac{\partial}{\partial z} \end{bmatrix}$ and defining $\boldsymbol{\Sigma}\left(\boldsymbol{u}\right)=\mathfrak{W}\left(\boldsymbol{u}\right)\;\underline{\mathbb{I}}\!-\!\underline{\mathbb{L}}^{T}(\boldsymbol{u})\;\boldsymbol{\sigma}\left(\boldsymbol{u}\right)$ $\mathfrak{W} = \frac{1}{2} \boldsymbol{\sigma}^T \boldsymbol{\varepsilon} \quad \underline{\mathbb{I}}^T = \{1, 1, 0, 0\}$ $\underline{\mathbb{L}}(\boldsymbol{u}) = \underline{\mathbb{L}} \underline{\mathbb{I}} \boldsymbol{u} \qquad \underline{\mathbb{L}} = \begin{bmatrix} \frac{\partial}{\partial x} & 0 & \frac{\partial}{\partial y} & 0 \\ 0 & \frac{\partial}{\partial y} & 0 & \frac{\partial}{\partial x} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial y} & \frac{\partial}{\partial x} \end{bmatrix} \qquad \underline{\mathbb{I}} = \begin{bmatrix} 1 & 0 \\ 0 & 1 \\ 1 & 0 \\ 0 & 1 \end{bmatrix}$

weak-form

$$\int_{\Omega} (\mathbb{L}\boldsymbol{v})^T \boldsymbol{\Sigma} \, l_z \, d\Omega = \int_{\Omega} (\boldsymbol{v})^T \, \boldsymbol{\rho} \, l_z \, d\Omega \qquad \boldsymbol{v} = \{v_x, v_y\}^T$$



unity with C^k-GFEM

Configurational forces method

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Concluding remarks

Post-processing of nodal configurational forces

$$\int_{\Omega} \left(\mathbb{L} \boldsymbol{v} \right)^T \boldsymbol{\Sigma} \, l_z \, d\Omega = \int_{\Omega} \left(\boldsymbol{v} \right)^T \boldsymbol{\rho} \, l_z \, d\Omega \,, \ \forall \boldsymbol{v} \mid \boldsymbol{v} = \, \boldsymbol{0} \text{ on } \partial\Omega$$

 $\Sigma(\boldsymbol{u}) = \mathfrak{W}(\boldsymbol{u}) \ \underline{\mathbb{I}} - \underline{\mathbb{L}}^{T}(\boldsymbol{u}) \ \boldsymbol{\sigma}(\boldsymbol{u})$ Eshelby tensor

$$\therefore \sum_{\alpha=1}^{N} \mathbb{U}_{\alpha}^{T} \left[-\int \int_{\Omega^{e}} \mathbb{B}_{\alpha}^{T} \Sigma \, l_{z} \, dx \, dy + \left(\int_{\Omega^{e}} \widehat{\varphi}_{\alpha}^{T} \rho_{\alpha} \, l_{z} \, dx \, dy \right) \right] = 0$$
where
$$\mathbb{B}_{\alpha} = \mathbb{L} \, \widehat{\varphi}_{\alpha}$$
thus, defining
$$\boldsymbol{G}_{\alpha}^{e} = \left\{ \begin{array}{c} \boldsymbol{G}_{x_{\alpha}}^{e} \\ \boldsymbol{G}_{y_{\alpha}}^{e} \end{array} \right\} = \int \int_{\Omega^{e}} \widehat{\boldsymbol{\varphi}}_{\alpha}^{T} \rho_{\alpha} \, l_{z} \, dx \, dy = \int \int_{\Omega^{e}} \mathbb{B}_{\alpha}^{T} \Sigma \, l_{z} \, dx \, dy$$

$$\boldsymbol{G}_{\alpha} = \bigcup_{e=1}^{N_{ad}} \boldsymbol{G}_{\alpha}^{e} \qquad \text{nodal} \text{ configurational force}$$



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Local measure using configurational forces

x-component of Eshelby stress tensor





Eshelby, *The force on an elastic singularity*. Philosophical Transactions of the Royal Society A: mathematical, physical and engineering sciences, 244 (1951)

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Mueller and Maugin, *On material forces and finite element discretizations.* Computational Mechanics, 29 (2002)

Glaser and Steinmann, **On material forces within the extended finite element method**. Proceedings of the sixth European Solid Mechanics Conference (2006)

Häusler, Lindhorst and Horst, **Combination of the material force concept and the extended finite element method for mixed mode crack growth simulations**. International Journal for Numerical Methods in Engineering, 85 (2011)



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Topologic enrichment pattern

M1









M4



- Branch functions on orange nodes;
- Uniform *p*-enrichment
- Local p-enrichment around the crack tip



Continuous partition of unity with C^k -GFEM

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Mixed mode loading

 $K_I = 1.0, K_{II} = 1.0$

$$\sigma_x = \frac{K_I}{\sqrt{2\pi r}} \cos\left(\frac{\theta}{2}\right) \left[1 - \sin\left(\frac{\theta}{2}\right) \sin\left(\frac{3\theta}{2}\right)\right] \\ - \frac{K_{II}}{\sqrt{2\pi r}} \sin\left(\frac{\theta}{2}\right) \left[2 + \cos\left(\frac{\theta}{2}\right) \cos\left(\frac{3\theta}{2}\right)\right]$$

$$\sigma_{y} = \frac{K_{I}}{\sqrt{2\pi r}} \cos\left(\frac{\theta}{2}\right) \left[1 + \sin\left(\frac{\theta}{2}\right) \sin\left(\frac{3\theta}{2}\right)\right] + \frac{K_{II}}{\sqrt{2\pi r}} \sin\left(\frac{\theta}{2}\right) \cos\left(\frac{\theta}{2}\right) \cos\left(\frac{3\theta}{2}\right)$$

$$\tau_{xy} = \frac{K_I}{\sqrt{2\pi r}} \cos\left(\frac{\theta}{2}\right) \sin\left(\frac{\theta}{2}\right) \cos\left(\frac{3\theta}{2}\right) \\ + \frac{K_{II}}{\sqrt{2\pi r}} \cos\left(\frac{\theta}{2}\right) \left[1 - \sin\left(\frac{\theta}{2}\right) \sin\left(\frac{3\theta}{2}\right)\right]$$





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Convergence in global values





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Convergence of J-integral



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Exact error dispersion: *y*-stress







C∞, 451 DOFs



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Exact error dispersion: *y*-stress



uniform polynomial enrichment, b = 1+

localized polynomial enrichment, p = 2



topologic pattern of

singular enrichment





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Exact error dispersion: *y*-stress



C0, 451 DOFs



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Collecting data of the three cases...





b=1, 191 DOFs, 145x10⁻³ *b*=1, *p*=2, 203 DOFs, 130x10⁻³ *b*=2, 451 DOFs, - 85x10⁻³ *b*=1, 451 DOFs, 62x10⁻³ *b*=1, *p*=2, 469 DOFs, 62x10⁻³ *b*=2, 841 DOFs, - 19x10⁻³



Continuous partition of unity with C^k -GFEM

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Angle of crack growth: θ_{ADV}

 $K_I = 1.0, K_{II} = 1.0$

$$\sigma_{x} = \frac{K_{I}}{\sqrt{2\pi r}} \cos\left(\frac{\theta}{2}\right) \left[1 - \sin\left(\frac{\theta}{2}\right) \sin\left(\frac{3\theta}{2}\right)\right] \\ - \frac{K_{II}}{\sqrt{2\pi r}} \sin\left(\frac{\theta}{2}\right) \left[2 + \cos\left(\frac{\theta}{2}\right) \cos\left(\frac{3\theta}{2}\right)\right]$$

$$\sigma_{y} = \frac{K_{I}}{\sqrt{2\pi r}} \cos\left(\frac{\theta}{2}\right) \left[1 + \sin\left(\frac{\theta}{2}\right) \sin\left(\frac{3\theta}{2}\right)\right] + \frac{K_{II}}{\sqrt{2\pi r}} \sin\left(\frac{\theta}{2}\right) \cos\left(\frac{\theta}{2}\right) \cos\left(\frac{3\theta}{2}\right)$$

$$\tau_{xy} = \frac{K_I}{\sqrt{2\pi r}} \cos\left(\frac{\theta}{2}\right) \sin\left(\frac{\theta}{2}\right) \cos\left(\frac{3\theta}{2}\right) \\ + \frac{K_{II}}{\sqrt{2\pi r}} \cos\left(\frac{\theta}{2}\right) \left[1 - \sin\left(\frac{\theta}{2}\right) \sin\left(\frac{3\theta}{2}\right)\right]$$





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Angle of crack advance: θ_{ADV}



Configurational forces are restorative forces !





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Angle of crack advance: θ_{ADV} , b = 2





- Continuous partition of unity with C^k-GFEM
- Defining an approximation subspace
- Quality assessment through global measures
- Configurational forces method
- Quality assessmen through local measures
- Smoothness, enrichments and conditioning
- Some improvements

Concluding remarks

Joining C^k-GFEM and C⁰-GFEM



Straightforward!!!



Concluding remarks

 C^{k} -GFEM shows better estimates of J and θ_{ADV} than C^{o} -GFEM:

- Probably due to the well determined flat-top;
- Smoothness seems to reduce transition effects around singular enrichment;
- Lower dependence with enrichment pattern;

- Lower dependence on the size of the region used to compute configurational forces;

-In general, C^k -GFEM combines:

- Higher regularity;
- Flat-top property;
- Definition on global coordinates -> admits extremely distorted meshes;
- Compact support.

Disavantages: - Lower polynomial reproducibility than C⁰-GFEM /XFEM;

- Higher integration cost;

Solution: - Apply smooth PoUs only at convenient zones of the model !

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